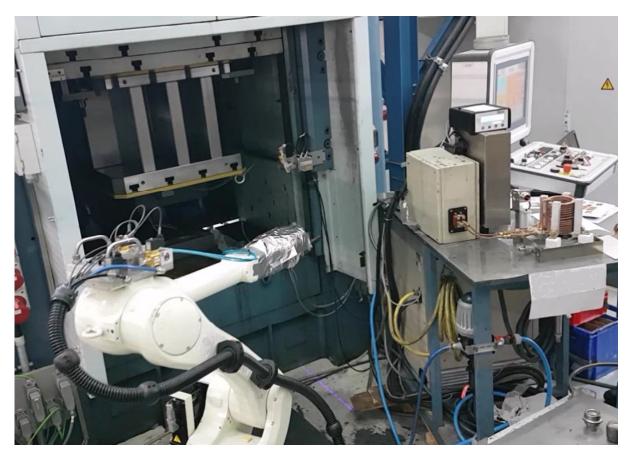
University of Stuttgart

Institute for Metal Forming Technology Equipment directory

Handling capability Kawasaki RS010L Robot



Purpose

Automation, accuracy, repeatability, security and control.

Specifications

- 6 axes articulated robot.
- Repeatibility ± 0.05 mm (at the tool mounting surface)
- Max. payload 10 kg
- Max. speed 13100 mm/s (at the tool mounting surface)
- Working range 1925 mm front, 1625 mm back
- Mass 230 kg (without base plate) + 40 kg controller unit

